ENGINEERING
TOMORROW

Technical Information

PLUS+1®
MC0XX-1XX Controllers Family

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Revision history

Table of revisions

Date	Changed	Rev
August 2022	Removed references to the amount of PVG valves that a DOUT can drive	0701
February 2020	Changed document number from 'BC00000227' and 'L1321895' to 'BC152986484529'	0603
October 2019	Replaced responsible user	0602
October 2019	Corrected table Danfoss crimp extraction tool part information, last row, Description: Extraction tool DEUTSCH 0411-240-2005; 16 to 20, 20 to 24 AW	0502
May 2019	Under Sensor power supply ratings, updated Specifications (all modules except MC050-055/05B) and Specifications (MC50-155/15B) tables	0501
April 2018	Added caution statement in DOUT and DOUT/PVGpwr topic and then added a new topic, Single Pulse Maximum Demagnetization Energy at 150 C	0401
August 2017	Minor correction	0302
May 2017	Recommended torque for fastners updated	0301
July 2016	Added notes regarding 5.7 V and high range under Analog (AIN) specifications table; then added High Range Input Impedance for Analog Inputs chart; updated Sensor power supply ratings: Specifications (MC50-155/15B)	0201
March 2016	Updated to Engineering Tomorrow design	0102
Mar 2014	First edition	AA

Contents

MC0XX-1XX Controller Family literature references

Literature title	Document type	Literature ID
PLUS+1® MC0XX-1XX Controller Family Technical Information	User Guide	**BC152986484529**
PLUS+1® MC012-110 and 112 Data Sheet	Data Sheet	**AI152986480902**
PLUS+1® GUIDE Software User Manual	Operation Guide	**AQ152886483724**

Comprehensive technical literature is online at *www.danfoss.com*

Technical Information (TI)

A TI is comprehensive information for engineering and service personnel to reference.

Module product Data Sheet (DS)

A module product DS contains summarized information and parameters that are unique to an individual PLUS+1® module, including:

- Numbers and types of inputs and outputs
- Module connector pin assignments
- Module maximum current capacity
- Module sensor power supply (if present) current capacity
- Module installation drawing
- Module weights
- Product ordering information

API specifications (API)

Module API specifications contain detailed information about the module BIOS. PLUS+1® BIOS functionality is pin dependent. Pins are defined in module data sheets as C (connector number) p (pin number).

API specifications include:

- Variable name
- Variable data type
- Variable direction (read/write)
- Variable function and scaling

Module API specifications are the definitive source of information regarding PLUS+1® module pin characteristics.

PLUS+1® GUIDE User Manual

The Operation Manual (OM) details information regarding the PLUS+1® GUIDE tool used in building PLUS +1® applications. This OM covers the following broad topics:

- How to use the PLUS+1® GUIDE graphical application development tool to create machine applications
- How to configure module input and output parameters
- How to download PLUS+1® GUIDE applications to target PLUS+1® hardware modules
- How to upload and download tuning parameters
- How to use the PLUS+1® Service Tool

User liability and safety statements

OEM responsibility

The OEM of a machine or vehicle in which Danfoss products are installed has the full responsibility for all consequences that might occur. Danfoss has no responsibility for any consequences, direct or indirect, caused by failures or malfunctions.

- Danfoss has no responsibility for any accidents caused by incorrectly mounted or maintained equipment.
- Danfoss does not assume any responsibility for Danfoss products being incorrectly applied or the system being programmed in a manner that jeopardizes safety.
- All safety critical systems shall include an emergency stop to switch off the main supply voltage for the outputs of the electronic control system. All safety critical components shall be installed in such a way that the main supply voltage can be switched off at any time. The emergency stop must be easily accessible to the operator.

Overview

MC0XX-1XX Controllers Family

PLUS+1® Mobile Machine Modules are designed to provide flexible, expandable, powerful and cost effective total machine management systems for a wide variety of vehicle applications.

These modules communicate with one another and other intelligent systems over a machine Controller Area Network (CAN) data bus.

PLUS+1® controller products utilize modular designs wherever possible. This modularity extends to product housings, connectors and control circuitry.

PLUS+1® hardware products are designed to be equally effective in a distributed CAN system, with intelligence in every node, or as stand-alone control for smaller machine systems.

PLUS+1® Compliant systems are incrementally expandable: additional modules can be easily added to the machine CAN bus to increase system capabilities or computational power.

Three standard housings, 12, 24, and 50 pin, cover this product line.

CAN

Input types

- Digital (DIN)
- Digital or Analog (DIN/AIN)
- Analog or Temperature or Rheostat (AIN/Temp/Rheo)
- Multifunction: Digital or Analog or Frequency (DIN/AIN/FreqIN)
- Multifunction: Digital or Analog or Frequency or Rheostat (DIN/AIN/FreqIN/Rheo)
- Fixed Range Analog or CAN shield (AIN/CAN shield)

Each PLUS+1® module input pin supports one of the above functional types. For pins with multiple functions, input configurations are user programmable using PLUS+1® GUIDE templates.

DIN

Digital inputs (DIN) connected to PLUS+1® dedicated digital input pins are debounced in software. Digital input debounce is defined as an input being in a given state for three samples before a state change is reported. The sample time is a function of application loop time.

Multifunction pins that are configured to be Digital input (DIN) are subject to the same update rates as the Analog input (AIN) function for that pin. Debounce is not used, as hysteresis is built into the function. The time to recognize a transition is dependent on the timing of the switch activation and the sample rate.

General response to input time

Description	Comment
Response to input below minimum voltage	Non-damaging, non-latching; reading saturates to the low limit.
Response to input above maximum voltage	Non-damaging, non-latching; reading saturates to the high limit.
Response to input open	Pin configuration dependent: No pull up/ no pull down = floating Pull up to 5 Vdc = 5 Vdc Pull down = 0 Vdc Pull up/ pull down = 2.5 Vdc
Voltage working ranges	Programmable (see specific data sheets for ranges).

Specifications

Description	Units	Minimum	Typical	Maximum	Comment
Input voltage range	V	0	—	36	
Rising threshold voltage	V	—	—	3.91	Guaranteed high voltage.
Falling threshold voltage	V	0.85	—	—	Guaranteed low voltage.
Input impedance	kΩ	230	233	236	No pull up or pull down.
Input impedance (5 V/GND)	kΩ	13.9	14.1	14.3	Pull up to +5 V or pull down to ground.

AIN

Analog inputs (AIN) specifications

Description	Units	Minimum	Typical	Maximum	Comment
Allowed voltage at pin	V	0	—	36	
Middle range					

CAN

Analog inputs (AIN) specifications (continued)

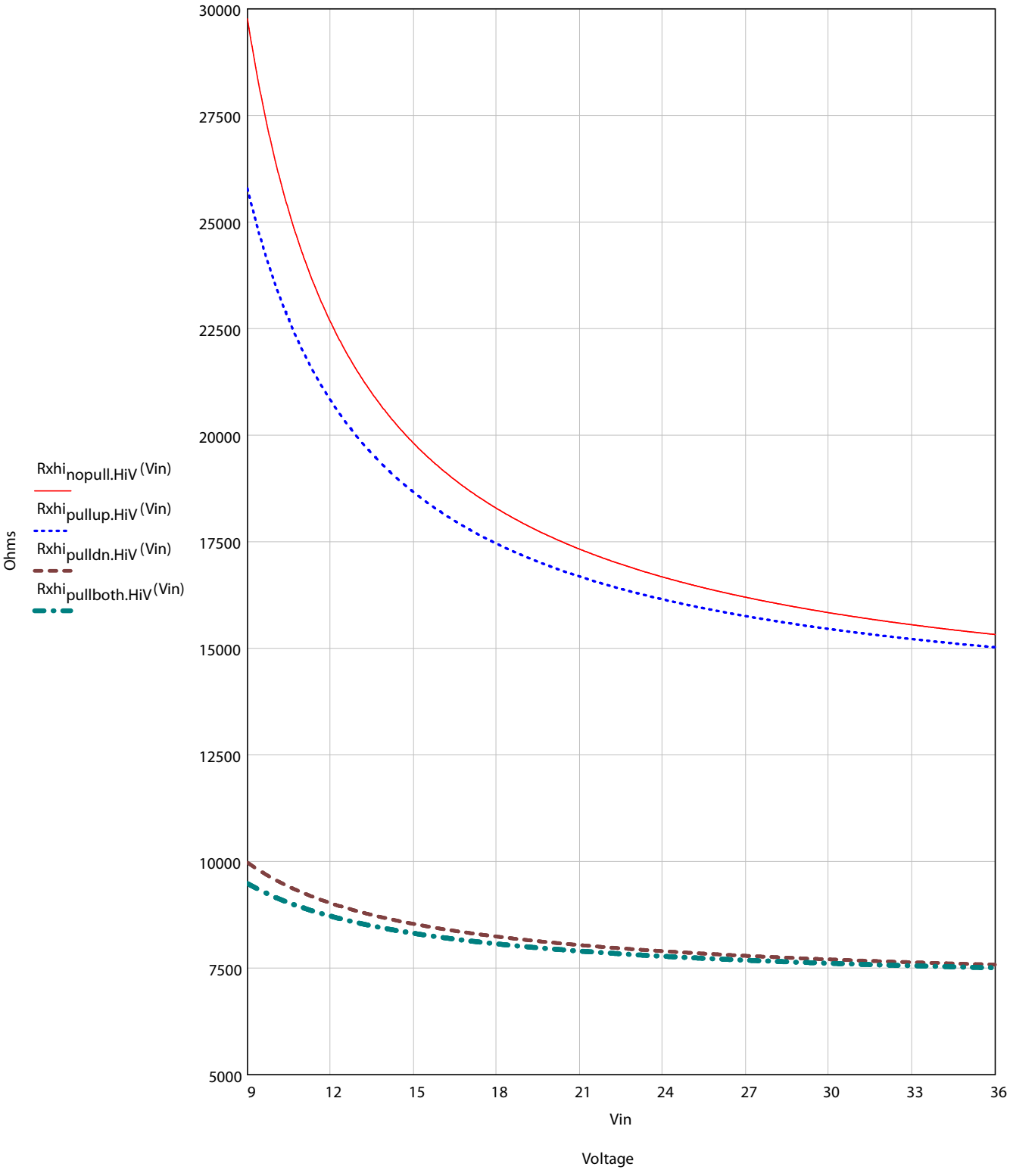
Description	Units	Minimum	Typical	Maximum	Comment
Minimum discernible voltage	mV	0	—	20	
Maximum discernible voltage	V	5.15	—	5.37	
Precision	mV	—	1.3	—	
Worst case error	mV	—	—	120	Over the full temperature range
Input impedance	kΩ	230	233	236	No pull up or pull down
Input impedance (5 V/GND)	kΩ	13.9	14.1	14.3	Pull up to +5 V or pull down to ground
Input impedance (2.5 V)	kΩ	7.1	7.3	7.4	Pull to +2.5 V
High range					
Minimum discernible voltage	mV	0	—	130	
Maximum discernible voltage	V	34.1	35.3	36.4	
Precision	mV	—	9	—	
Worst case error	V	—	—	1.1	Over the full temperature range
Input impedance	kΩ	108	109	111	No pull up or pull down.
Input impedance (5 V/GND)	kΩ	13.0	13.2	13.4	Pull up to +5 V or pull down to ground.
Input impedance (2.5 V)	kΩ	6.9	7.0	7.1	Pull to +2.5 V

For voltages > 5.7 V, see *High range input impedance for analog inputs* on page 9.

In high range the input impedance decreases as the input voltage increases.

CAN

High range input impedance for analog inputs



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A/D refresh rate

Analog to Digital (A/D) refresh rates for individual PLUS+1® MC0XX-1XX family modules and expansion modules are listed in the following table.

PLUS+1® module	A/D refresh rate
MC012-110/112	All: 1.00 ms
MC024-110/112	All: 1.00 ms
MC024-120/122	All: 1.00 ms
MC050-110/112	All: 1.00 ms
MC050-120/122	All: 1.00 ms
MC050-155/15B	All: 1.00 ms
IOX012-110	Refresh rate is a function of CAN message frequency
IOX024-120	Refresh rate is a function of CAN message frequency

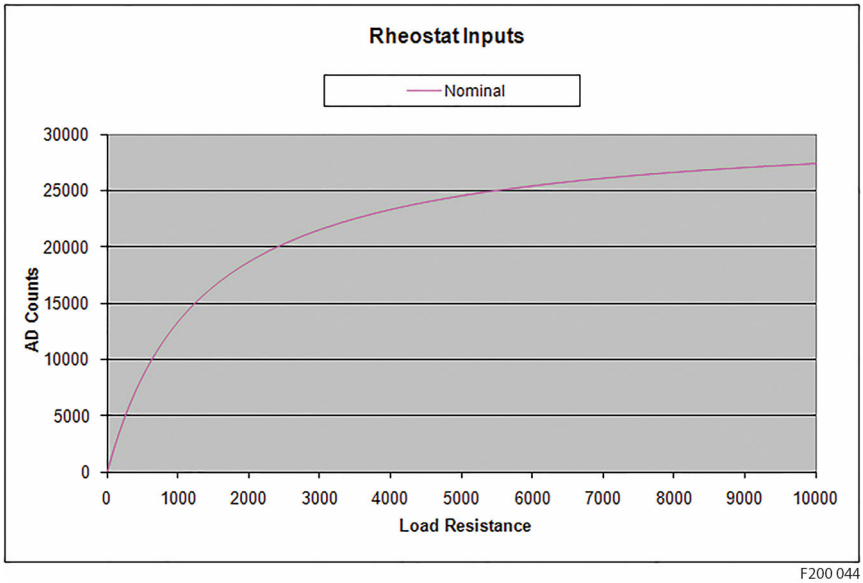
AIN/Temp/Rheo; Din/AIN/FreqIN/Rheo

Analog/Temperature/Rheostat (AIN/Temp/Rheo);

Digital/Analog/Frequency/Rheostat (Din/AIN/FreqIN/Rheo)

When configured as a resistance/rheostat/temp sensor input, the device will provide up to 3.76 mA current to an external load which can then be measured. The equation for calculating AD counts for a given load is: AD counts = (30996 x RL / (RL + 1322)). The following chart shows the relationship between AD counts and load.

Rheostat inputs



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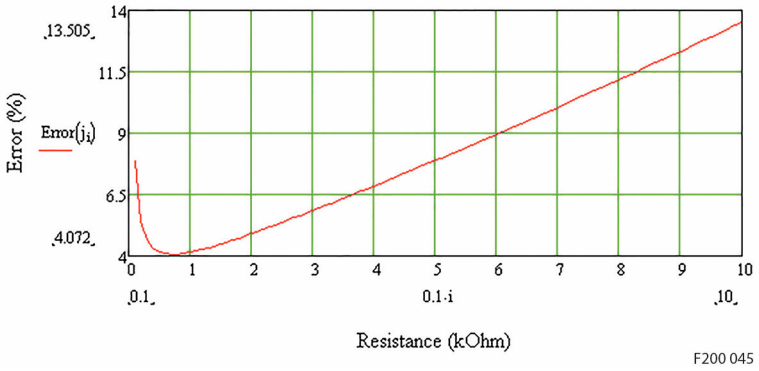
The following chart shows the relationship between load resistance versus worst case error over the full operating temperature -40° C to 70° C (-40° F to 158° F).

CAN

Load resistance versus worst case error



DIN/AIN/FreqIN; Din/AIN/FreqIN/Rheo (All models)

The characteristics of Digital/Analog/Frequency (DIN/AIN/FreqIN) pins are PLUS+1® GUIDE software controlled. The input can be digital, analog or frequency.

Inputs can be pulled to 5 Vdc, pulled to ground, pulled to 2.5 Vdc, or no pull-up/pull-down.

DIN/AIN/FreqIN general information

Description	Comment
Response to input below minimum voltage	Non-damaging, non-latching; reading saturates to the low limit.
Response to input above maximum voltage	Non-damaging, non-latching; reading saturates to the high limit.
Expected measurement	Frequency (Hz)
	Period (0.1 µsec)
	Channel to channel phase shift (paired inputs . . .) (0.1 ms).
	PWM duty cycle (0.01%)—Duty cycle measurement only valid up to 5 kHz (FreqIN).
	Edge count.
	Quadrature count (paired inputs driven from a quadrature encoder).
Pull up/pull down configuration	No pull down/ pull up is standard with pull up or pull down programmable; failure modes are detectable.

As with analog input pins, values in the following table assume software compensation for AD converter offset errors.

Specifications

Description	Units	Minimum	Typical	Maximum	Comment
Allowed voltage at pin	V	0	—	36	
Frequency range	Hz	0	—	10,000	In steps of 1 Hz.
Frequency range when input is used as quad count or phase shift	Hz	0	—	5000	In steps of 1 Hz.
Low range					
Minimum discernible voltage	mV	—	—	12.9	
Maximum discernible voltage	mV	341	368	394	

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Specifications (continued)

Description	Units	Minimum	Typical	Maximum	Comment
Precision	mV	—	0.09	—	
Worst case error	mV	—	—	27	Over the full temperature range.
Rising voltage threshold	V	—	—	0.30	Voltage required for frequency input to read high.
Falling voltage threshold (low range)	V	0.04	—	—	Voltage required for frequency input to read low.
Middle range					
Minimum discernible voltage	mV	0	—	20	
Maximum discernible voltage	V	5.14	5.26	5.37	
Precision	mV	—	1.3	—	
Worst case error	mV	—	—	120	Over the full temperature range.
Rising voltage threshold	V	—	—	3.92	Voltage required for frequency input to read high.
Falling voltage threshold	V	0.84	—	—	Voltage required for frequency input to read low.
High range					
Minimum discernible voltage	mV	0	—	130	
Maximum discernible voltage	V	34.1	35.3	36.4	
Precision	mV	—	9	—	
Worst case error	V	—	—	1.1	Over the full temperature range.
Rising voltage threshold	V	—	—	26.52	Voltage required for frequency input to read high.
Falling voltage threshold	V	5.61	—	—	Voltage required for frequency input to read low.
High range DAF					
Input impedance	kΩ	108	—	111	No pull up or pull down.
Input impedance (5 V/GND)	kΩ	13.0	—	13.4	Pull up to +5 V or pull down to ground.
Input impedance (2.5 V)	kΩ	6.64	—	7.02	Pull to +2.5 V.
Middle and low range DAF					
Input impedance	kΩ	230	—	236	No pull up or pull down.
Input impedance (5 V/GND)	kΩ	13.9	—	14.3	Pull up to +5 V or pull down to ground.
Input impedance (2.5 V)	kΩ	7.1	—	7.4	Pull to +2.5 V.
High range DAFR					
Input impedance	kΩ	63	—	95	No pull up or pull down.

CAN

Specifications (continued)

Description	Units	Minimum	Typical	Maximum	Comment
Input impedance (5 V/GND)	kΩ	12	—	13.1	Pull up to +5 V or pull down to ground.
Input impedance (2.5 V)	kΩ	6.64	—	7.02	Pull to +2.5 V.
Middle and low range DAFR					
Input impedance	kΩ	91	—	175	No pull up or pull down.
Input impedance (5 V/GND)	kΩ	12.7	—	14.0	Pull up to +5 V or pull down to ground.
Input impedance (2.5 V)	kΩ	6.86	—	7.26	Pull to +2.5 V.

If the frequency goes to zero, the data will not decay over time, it will be updated once a new pulse is seen, or times out. It is possible to monitor the count of pulses to know when the frequency reading is updated.

Output types

- Digital (DOUT)
- Digital/PVG valve reference power (DOUT/PVGpwr)
- Pulse width modulated (PWM/DOUT/PVGOUT)

Output pins available on MC0XX-1XX Controller Family

PLUS+1® module	DOUT (3 A)	DOUT/PVGpwr (3 A)	PWMOUT/DOUT/PVGOUT (3 A)
MC012-110/112			2
MC024-110/112			4
MC024-120/122			8
MC050-110/112	3	3	10
MC050-120/122	6	2	6
MC050-155/15B	1		2
IOX012-110			2
IOX024-120			8
OX012-110			6
OX024-110	4	2	10

PLUS+1® modules feature user-configurable output pin parameters. Output pin parameters are configured using PLUS+1® GUIDE templates.

Warning

Unintended movement of the machine or mechanism may cause injury to the technician or bystanders. The module will be powered up if battery voltage is applied to the module's output pin. To protect against unintended movement, secure the machine.

Caution

Warranty will be voided if module is damaged.
Avoid significant current driven back through an output pin.

CAN

DOUT and DOUT/PVGpwr

Digital (DOUT) and Digital/PVG Reference Power (DOUT/PVGpwr).

Digital outputs can source up to 3 A

- Only MC050-110, MC050-120, and OX024-110 modules have DOUT.
- DOUT and DOUT/PVG Pwr pins are pair limited and a function of temperature.

  Output per pair is: 6 A maximum at 25° C [77° F]. Output per pair is 4 A maximum at 70° C [158° F]
- MC050-110 pairs are: C1p31 and C1p32, C1p33 and C1p34, C1p35 and C1p36
- MC050-120 pairs are: C1p33 and C1p34, C1p35 and C1p36, C1p37 and C1p38, C1p39 and C1p40
- OX024-110 pairs are: C1p6 and C1p7, C1p8 and C1p9, C1p10 and C1p11
- Example: at a module temperature of 70° C [158° F], if C1p31 is sourcing 2.5 A, the most current that can be sourced on its paired pin C1p32 is 1.5 A

Caution

Driving an inductance with higher turn off energy, than shown in the graph *Single Pulse Maximum Demagnetization Energy at 150 C* on page 15, may cause damage to the device. This can be avoided by adding an external recirculation diode or driving with a PWM output.

General

Description	Comment
Configuration	Sourcing only.
Type	Linear switching.
Short circuit to ground protection	Non-damage, current/thermal limit with status indication; automatic latch off /resume.
Open circuit detection	Fault indication provided. The GUIDE Pin Status requires a load of 500 mA to be connected or an open fault will be declared.
Parallel operation	Digital outputs from the same module are capable of being connected together such that the net current rating is the sum of the individual ratings; timing is resolved by the operating system; diagnostic capability is maintained.
Shut off	Processor control with hardware WatchDog override.

Specifications

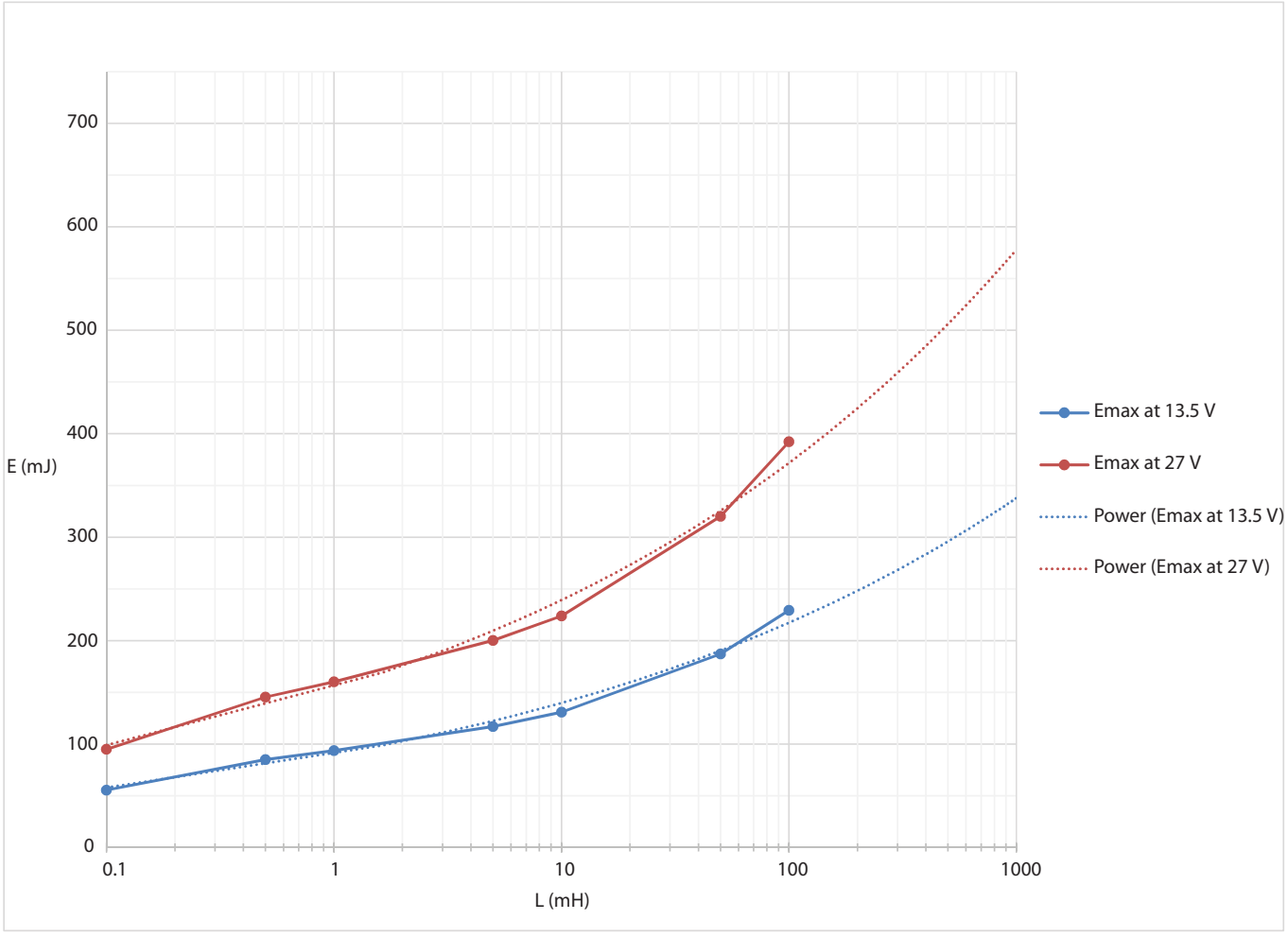
Description	Units	Minimum	Maximum	Comment
Allowed voltage at pin	V	0	36	See *Caution statement*
Output voltage, energized state	V	Vbatt-1.0	Vbatt	Over all load conditions.
Output voltage, off state	V	0	0.1	At Rload=200 Ω
Output current range for a status bit to read OK	A	0.5	3	See *note regarding pair*

Do not connect a digital output to battery+ (back drive) without a series diode.

CAN

Single Pulse Maximum Demagnetization Energy at 150 C

1. The high side driver (HSD) has a built in voltage clamp for fast demagnetization of inductive loads.
2. The turn off energy is absorbed by the HSD.
3. If the turn off energy is above the HSD maximums shown in following graph, there will be two options:
   a. Use external clamping or a recirculating diode.
   b. Use a PWM output that has built in recirculation/clamping.
4. Power trend lines were added to extend the graphs for inductances over 100 mH.



PWMOUT/DOUT/PVGOUT

All PLUS+1® module proportional outputs are Pulse Width Modulated (PWM). PWM frequency is software adjustable using PLUS+1® GUIDE. A low frequency dither may also be added with software to some outputs (see individual module API specifications for PWM outputs that support dither). There are two modes of PWM operation: open loop and closed loop (current control).

In open loop mode, current can be sourced or sunk, but the output is a PWM duty cycle. Current feedback may be monitored in open loop mode, but the output is a constant voltage, not a constant current. The signal line of PVG valves can be driven with an open loop PWM. The PWM driving the control signal must be set to 0 at the same time as the digital output driving the PVE power pin is set to 0.

CAN

In open loop mode, current can be sourced or sunk (all modules are limited to 8 amps sinking), but the output is a PWM duty cycle. Current feedback may be monitored in open loop mode, but the output is a constant voltage, not a constant current. PVG valves may be driven with open loop PWM.

In closed loop mode, current is sourced and a constant current is maintained by the module's operating system using internal current feedback. Load impedance must not exceed 65 ohms.

In closed loop mode, the maximum current is limited by measuring the feedback current. There is no thermal protection. If the maximum current is exceeded, the controller kernel will shut down the output and latch it. The kernel also limits how quickly the output can be repowered (250 ms). The output cannot be reset until the command goes to 0 or False (if configured as a digital output).

Proportional outputs that are used as a digital sinking output have a potential for a leakage current of up to 5 mA when off.

PWM output are phase shifted to reduce input current ripple.

Refer to individual module data sheets for the maximum allowable output current for each PLUS+1® module.

General

Description	Comment
Configuration	Sourcing or sinking
Type (Linear vs. PWM)	PWM
Operating modes	Programmable: closed loop current or open loop voltage (duty cycle)
Dual coil PCPs	Compensated for induced currents in a non-driven coil (closed loop mode)
Short circuit to ground	Output fully protected against damage and fault detected
Mode selection (current or voltage) and full scale current ranges	Programmable

Do not connect a digital output to battery+ (back drive) without a series diode.

PLUS+1® PWM output circuits are not designed to be used as inputs. Output current feedback readings should be used for fault checking only.

Warning

Unintended movement of the machine or mechanism may cause injury to the technician or bystanders. The module will be powered up if battery voltage is applied to the module's output pin. To protect against unintended movement, secure the machine.

Caution

Warranty will be voided if module is damaged.
Avoid significant current driven back through an output pin.

Specifications

Description	Units	Minimum	Maximum	Comment
Full scale proportional current output	mA	10	3000	The current may accidentally be exceeded in open loop mode. If the current exceeds the trip point, the output will be latched off.
Output voltage, 100% duty cycle	V	0	Vbatt-1	
Output resolution of 3 A	mA		0.25	
Repeatability of full range	% of full scale		0.5	

CAN

Specifications (continued)

Description	Units	Minimum	Maximum	Comment
Absolute accuracy of full range	% of full scale		3	1% typical. Offsets removed when command is Ø.
Output settling time	ms		100	Depends on load characteristics.
PWM frequency	Hz	33	4000	Some pins have a fixed frequency, consult module application program interface (API).
Dither frequency	Hz	33	250	Increased in steps, see module API.
Dither amplitude	A	0	0.5	Increased in steps, see module API.
Over-current trip point	A	5	5.25	There is over-current protection built into each output driver. If the instantaneous current exceeds the trip point, the driver is latched off. GUIDE application software can reset the latch and attempt to drive current again.

Controller Area Network (CAN)

CAN system design

All PLUS+1® modules have CAN ports that conform to CAN 2.0B specifications, including CAN shield.

CAN1 port and CAN2 port on MC050-155/15B controllers cannot be used to download PLUS+1® GUIDE application programs.

Specifications for terminating resistor

Each end of the main backbone of the CAN bus must be terminated with an appropriate resistance to provide correct termination of the CAN_H and CAN_L conductors. This termination resistance should be connected between the CAN_H and CAN_L conductors.

Specifications

Description	Units	Minimum	Maximum	Nominal	Comment
Resistance	Ω	110	130	120	Minimum power dissipation 400 mW (assumes a short of 16 Vdc to CAN_H).
Inductance	µH		1		

Notes on CAN Bus installation

Total bus impedance should be 60 Ω.

The CAN transceiver will be damaged by any voltage outside of allowable range, (-27 to +36 Vdc), even with a very short pulse.

If using shielded cable, the shield must be grounded to the machine ground at one point only; preferably at the mid-point of the CAN bus. Each PLUS+1® module CAN shield pin must be connected to the cable shield.

Expansion module CAN Bus loading

System designers incorporating PLUS+1® expansion modules in their applications should be aware of PLUS+1® CAN bus loading and controller memory usage during system design. Each expansion module is associated with a PLUS+1® controller and uses part of the controller's memory resources for inter-module communications. The following table can be used to estimate system CAN bus loading and the memory impact of I/O modules on their associated controller.

Estimated usage of memory and communication resources

Description	IX012-010	IX024-010	OX012-010	OX024-010	IOX012-010	IOX024-20
Estimated module bus load (using default update and 250K bus speed)	4%	10%	11%	27%	11%	27%
Estimated module bus load (using 70 ms updates and 250K bus speed)	2%	5%	3%	8%	4%	8%
RAM usage on MC012-XXX	9%	12%	9%	14%	9%	17%
RAM usage on MC024-010	9%	12%	9%	14%	9%	17%

Controller Area Network (CAN)

Estimated usage of memory and communication resources (continued)

Description	IX012-010	IX024-010	OX012-010	OX024-010	IOX012-010	IOX024-20
RAM usage on MC050-010, MC050-020	1%	1%	1%	2%	1%	2%
RAM usage on MC050-055	1%	1%	1%	2%	1%	0%
ROM usage on MC012-XXX	8%	11%	12%	18%	10%	19%
ROM usage on MC024-010	8%	11%	12%	18%	10%	20%
ROM usage on MC050-010, MC050-020	3%	4%	4%	6%	3%	8%
ROM usage on MC050-055	3%	4%	4%	6%	3%	8%

Product ratings

Power

Module supply voltage/maximum current ratings

PLUS+1® modules are designed to operate with a nominal 9 to 36 Vdc power supply.

The modules will survive with full functionality if the supply voltage remains below 36 Vdc.

Specifications

Description	Units	Minimum	Maximum	Comment
Allowed voltage at pin	V	0	36	
Allowed module current	A	0	120	

Caution

PCB damage may occur.
To prevent damage to the module all module power supply + pins must be connected to the vehicle power supply to support advertised module maximum output current capacity. DO NOT use module power supply + pins to supply power to other modules on a machine.

Sensor power supply ratings

PLUS+1® modules that support sensor inputs are provided with dedicated, software adjustable, regulated sensor power supply and ground pins. Refer to individual product data sheets for sensor power supply current ratings.

The sensor power is nominally 5 Vdc, unless otherwise noted on the product data sheet.

General

Description	Comment
Short circuit to ground	Output is not damaged and fault is detected.
Short circuit to battery +	Output is not damaged and fault is detected.

Specifications (all modules except MC050-055/05B)

Description	Units	Minimum	Maximum	Comment
Output short circuit voltage	V		36	
Output voltage (actual)	V	4.88	5.12	
Output voltage (internally measured)	V	4.64	5.32	
Output current	mA			Refer to individual data sheets for sensor power supply ratings.
Output Load Capacitance	µF		10	
Hold up time after power loss	ms	5	15	

MC0XX-1XX controllers feature two additional levels of regulated power: 1.6 Vdc and 3.3 Vdc. The PLUS +1® GUIDE application developer can detect open and short digital inputs, when these power supplies are used in conjunction with DIN/AIN inputs.

Product ratings

Specifications (MC50-155/15B)

Description	Units	Minimum	Maximum	Comment
Output short circuit voltage	V		36	
Output voltage, sensors (actual)	V	4.56	5.10	Sensor power supply drops below minimum if controller power supply is less than 9 Vdc.
Output voltage, sensors (internally measured)	V	4.34	5.33	
Output voltage, DIN diagnostics	V	1.58	1.71	Nominal 1.6
Output voltage, DIN diagnostics	V	3.16	3.39	Nominal 3.3

PVG valve power supply ratings

DOUT/PVGpwr pins can provide the battery supply voltage required by Danfoss PVG valve electronics for those control strategies requiring application software control of the valve power source.

When enabled, the DOUT/PVGpwr pin passes battery (reference) voltage to the PVG valve electronics. Refer to individual module API documents for PVG power pin characteristics.

Non-volatile memory read/write ratings

FRAM memory

Write/erase cycles

Description	Minimum	Maximum	Comment
FRAM write/erase cycles	100 trillion		Minimum valid over entire operating temperature range.

FRAM used in the MC0XX-1XX controller, is rated for 100 trillion read/write cycles per sector. Sector size is 32 bits. When a value is written to FRAM, all 32 bits in a particular sector are always written, regardless of the size of the saved value. If the value being saved in a sector is less than 32 bits (such as. U8, S16, BOOL, etc) adjacent bits in the same FRAM sector are rewritten with their previous value. The implication of this memory property is that if two values are being written to the same memory sector, the useful life of the sector is determined by the value being written most frequently. If that value exceeds 100 trillion read/write cycles, all values in the sector may be compromised if the useful life is exceeded.

Vault memory

Some variants of PLUS+1® modules have 2 Mbyte of serial flash vault memory (also referred to as *application logging memory*).

Application developers can use this memory to log machine event data and use the PLUS+1® Service Tool to extract the logged data. As there is no real time clock on PLUS+1® modules, vault memory is not time stamped.

Accessing non-volatile or application log memory can delay the service tool scan.

Product ratings

General ratings

MC controllers general ratings

Description	Units	Minimum	Maximum	Comment
Operating temperature	°C [°F]	-40 [-40]	70 [158]	Maximum operating temperature for MC012-026/029 modules is 105° C (221° F).
Storage temperature	°C [°F]	-40 [-40]	85 [185]	Maximum storage temperature for MC012-026/029 modules is 105° C (221° F).
Allowable module supply voltage	Vdc	9	36*	Minimum allowable supply voltage for the MC038-010 module CPU power pin is 6 Vdc.
Module sensor supply voltage	Vdc	4.8	5.2	Sensor voltage drops below the minimum value if module supply voltage < 9 Vdc. Exception for MC050-055/05B and MC024-01A, see *Sensor power supply ratings*.
Analog input voltage levels	Vdc		36*	
Allowable output load current (per pin)	A			See individual module date sheets.
Module allowable total output current	A			See individual module data sheets.
All modules Ingress Protection (IP) rating**				IP 67
All modules CE rating				CE compliant.

* MC050-055/05B input voltage maximum is limited to 16 Vdc.

** The PLUS+1® modules IP 67 rating is only valid when the module mating connector is in place and unused connector pin positions have sealing plugs installed.

Environmental testing criteria

Climate environment

Description	Applicable standard	Comment
Storage temperature	IEC 60068-2-1, test Ab, IEC 60068-2-2 test Bb	
Operating temperature	IEC 60068-2-1, test Ab, IEC 60068-2-2 test Bd	
Thermal cycle	IEC 60068-2-2, test Na, IEC 60068-2-38 (partial)	
Humidity	IEC 60068-2-78, IEC 60068-2-30 test Db	Damp heat steady state and cyclic.
Degree of protection	IEC 60529	

Chemical environment

Description	Applicable standard	Comment
Salt mist	IEC 60068-2-58 test Kb	
Chemical resistance	ISO 16750-5	

Product ratings

Mechanical environment

Description	Applicable standard	Comment
Vibration	IEC 60068-2-6 test Fc, IEC 6008-2-64 test Fh	
Bump	IEC 60068-2-29 test Eb	
Shock	IEC 60068-2-27 test Ea	
Free fall	IEC 60068-2-32 test Ed	

Electrical/electromagnetic

Description	Applicable standard	Comment
EMC emission	ISO 13766, SAE J1113-13	Electromagnetic compatibility for earth moving machinery.
EMC immunity	ISO 13766	Electromagnetic compatibility for earth moving machinery.
Electrostatic discharge	EN 60-1 000-4-2	
Auto electrical transients	ISO 7637-2, ISO 7637-3	
Short circuit protection	Danfoss test	Inputs and outputs survive continuous short circuit. Normal function resumes when short is removed.
Reversed polarity protection	Danfoss test	Survives reverse polarity at supply voltage for at least five minutes.

Modules housing

MC0XX-1XX module housing features are ultrasonically welded together with an assembly that is tamper-proof. Once assembled at the factory, the housing cannot be opened for service.

Caution

Warranty will be voided if device is opened.
Device is not field serviceable. Do not open the device.

Product installation and start-up

Connectors

PLUS+1® modules use DEUTSCH connectors. Danfoss assembles mating connector kits, referred to as a bag assembly.

Mating connector bag assembly ordering information is found in module product data sheets.

DEUTSCH mating connector part information

Description	12 pin module	24 pin module	50 pin module
Crimp tool	HDT48-00 (solid contacts) (20 to 24 AWG)	HDT48-00(solid contacts) (20 to 24 AWG)	HDT48-00 (solid contacts) (20 to 24 AWG)
	DTT20-00 (stamped contacts) (16 to 20 AWG)	DTT20-00 (stamped contacts) (16 to 20 AWG)	DTT20-00 (stamped contacts) (16 to 20 AWG)
Contacts	Solid: 0462-201-2031 (20 to 24 AWG)	Solid: 0462-201-2031 (20 to 24 AWG)	Solid: 0462-201-2031 (20 to 24 AWG)
	Stamped: 1062-20-0144 (16 to 20 AWG)	Stamped: 1062-20-0144 (16 to 20 AWG)	Stamped: 1062-20-0144 (16 to 20 AWG)
Connector plug	Gray A-Key DTM 06-125A	Gray A-Key DTM 06-12SA Black B-Key DTM 06-12SBA	DRC26-50S01
Wedge	WM-12S	WM-12S	Not required
Strip length	3.96 to 5.54 mm [0.156 to 0.218 in]	3.96 to 5.54 mm [0.156 to 0.218 in]	3.96 to 5.54 mm [0.156 to 0.218 in]
Real seal maximum insulation OD	3.05 mm [0.120 in]	3.05 mm [0.120 in]	2.41 mm [0.095 in]
Sealing plugs	0413-204-2005	0413-204-2005	0413-204-2005

Danfoss mating connector part information

Description	12 pin module	24 pin module	50 pin module
Mating connector bag assembly (20 to 24 AWG)	10100944	10100945	10100946
Mating connector bag assembly (16 to 20 AWG)	10102025	10102023	10102024

Danfoss crimp extraction tool part information

Description	Part number
Crimp tool for 20 to 24 AWG	10100745
Crimp tool for 16 to 20 AWG	10102028
Extraction tool DEUTSCH 114010; 12 AWG	11068808
Extraction tool DEUTSCH 0411-240-2005; 16 to 20, 20 to 24 AWG	10100744

Mounting

PLUS+1® MC0XX-1XX 12, 24, and 50 pin modules can be mounted in one of three ways:

- End (bulkhead) installation
- Up to 3 units stacked on one another
- Individually side mounted

Care must be taken to insure that the module connector is positioned so that moisture drains away from the connector.

Product installation and start-up

If the module is side or stack mounted, provide a drip loop in the harness. If the module is mounted vertically, the connector should be on the bottom of the module.

Provide strain relief for mating connector wires.

Caution

Module damage may occur.
Use caution when installing modules. Due to the size of the mating connector wire bundle, it is possible to twist off the end cap of the module if excessive pressure is applied during the installation of harness strain relief.

Fasteners

Recommended outer diameter (OD)	Recommended torque
6.0 mm (0.25 in)	2.26 N•m (20 in•lbs)

Machine diagnostic connector

It is recommended that a diagnostic connector be installed on machines that are controlled by PLUS+1® modules. The connector should be located in the operator's cabin or in the area where machine operations are controlled and should be easily accessible.

Communication (software uploads and downloads and service and diagnostic tool interaction) between PLUS+1® modules and personal computers is accomplished over the vehicle CAN network. The diagnostic connector should tee into the vehicle CAN bus and have the following elements:

- CAN +
- CAN -
- CAN shield

Grounding

Proper operation of any electronic control system requires that all control modules including displays, microcontrollers and expansion modules be connected to a common ground. A dedicated ground wire of appropriate size connected to the machine battery is recommended.

Hot plugging

Machine power should be off when connecting MC0XX-1XX modules to mating connectors.

Machine wiring guidelines

- Protect wires from mechanical abuse, run wires in flexible metal or plastic conduits.
- Use 85˚ C (185˚ F) wire with abrasion resistant insulation and 105˚ C (221˚ F) wire should be considered near hot surfaces.
- Use a wire size that is appropriate for the module connector.
- Separate high current wires such as solenoids, lights, alternators or fuel pumps from sensor and other noise-sensitive input wires.
- Run wires along the inside of, or close to, metal machine surfaces where possible, this simulates a shield which will minimize the effects of EMI/RFI radiation.
- Do not run wires near sharp metal corners, consider running wires through a grommet when rounding a corner.
- Do not run wires near hot machine members.
- Provide strain relief for all wires.
- Avoid running wires near moving or vibrating components.

Product installation and start-up

- Avoid long, unsupported wire spans.
- Ground electronic modules to a dedicated conductor of sufficient size that is connected to the battery (-).
- Power the sensors and valve drive circuits by their dedicated wired power sources and ground returns.
- Twist sensor lines about one turn every 10 cm (4 in).
- Use wire harness anchors that will allow wires to float with respect to the machine rather than rigid anchors.

Machine welding guidelines

Warning

High voltage from power and signal cables may cause fire or electrical shock, and cause an explosion if flammable gasses or chemicals are present.
Disconnect all power and signal cables connected to the electronic component before performing any electrical welding on a machine.

The following is recommended when welding on a machine equipped with electronic components:

- Turn the engine off.
- Remove electronic components from the machine before any arc welding.
- Disconnect the negative battery cable from the battery.
- Do not use electrical components to ground the welder.
- Clamp the ground cable for the welder to the component that will be welded as close as possible to the weld.

PLUS+1® USB/CAN Gateway

Communication (software uploads and downloads and service and diagnostic tool interaction) between PLUS+1® modules and a personal computer (PC) is accomplished using the vehicle's PLUS+1® CAN network.

The PLUS+1® CG150-2 USB/CAN gateway provides the communication interface between a PC USB port and the vehicle CAN bus. When connected to a PC, the gateway acts as a USB slave. In this configuration, all required electrical power is supplied by the upstream PC host. No other power source is required.

Refer to the *PLUS+1® GUIDE Software User Manual*, **AQ152886483724**, for gateway set-up information. Refer to the *CG150-2 USB/CAN Gateway Data Sheet*, **AI152986480800**, for electrical specifications and connector pin details.

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Local address:

Danfoss
Power Solutions (US) Company
2800 East 13th Street
Ames, IA 50010, USA
Phone: +1 515 239 6000

Danfoss
Power Solutions GmbH & Co. OHG
Krokamp 35
D-24539 Neumünster, Germany
Phone: +49 4321 871 0

Danfoss
Power Solutions ApS
Nordborgvej 81
DK-6430 Nordborg, Denmark
Phone: +45 7488 2222

Danfoss
Power Solutions Trading (Shanghai) Co., Ltd.
Building #22, No. 1000 Jin Hai Rd
Jin Qiao, Pudong New District
Shanghai, China 201206
Phone: +86 21 2080 6201